

# Math 212: Answers to Assignment 2

## Section 2.2

**#1)** To show that  $A = \{(x, y) \mid -1 < x, y < 1\}$  is open, we need to show that for any point  $\vec{x}_0 = (x_0, y_0)$ , we can find an  $\varepsilon > 0$  such that  $D_\varepsilon(\vec{x}_0) \subset A$ . Let  $\varepsilon = \min\{1 - |x_0|, 1 - |y_0|\}$ . For any  $\vec{x} = (x, y) \in D_\varepsilon(\vec{x}_0)$  we have

$$\|\vec{x}_0 - \vec{x}\| < \varepsilon \Rightarrow (x - x_0)^2 + (y - y_0)^2 < \varepsilon^2 \Rightarrow |x - x_0|, |y - y_0| < \varepsilon$$

So,

$$|x_0| \leq |x_0 - x| + |x| < 1 - |x_0| + 1 \Rightarrow 2|x_0| < 2 \Rightarrow |x_0| < 1$$

$$|y_0| \leq |y_0 - y| + |y| < 1 - |y_0| + 1 \Rightarrow 2|y_0| < 2 \Rightarrow |y_0| < 1$$

So,  $D_\varepsilon(\vec{x}_0) \subset A \Rightarrow A$  is open.  $\square$

**#5a)** Since  $x^3y$  is continuous, the limit is equal the the function evaluated at  $(0, 1)$ , so

$$\lim_{(x,y) \rightarrow (0,1)} x^3y = 0^3 \cdot 1 = 0$$

**#6a)** As in #5a above, we just need to calculate  $e^0 \cdot 1 = 1$

**#6b)** This time,

$$f(x) = \frac{\sin^2 x}{x}$$

doesn't have a value at  $x = 0$ , but the limit on the top and the bottom of the fraction both equal to 0. So we will use L'Hopital's rule:

$$\lim_{x \rightarrow 0} \frac{\sin^2 x}{x} = \lim_{x \rightarrow 0} \frac{2 \sin x \cos x}{1} = 0$$

**#6c)** Again, we need L'Hopital's rule (twice):

$$\lim_{x \rightarrow 0} \frac{\sin^2 x}{x^2} = \lim_{x \rightarrow 0} \frac{2 \sin x \cos x}{2x} = \lim_{x \rightarrow 0} \frac{2 \cos^2 x - 2 \sin^2 x}{2} = 1$$

## Section 2.3

#1a)

$$\frac{\partial}{\partial x} f = y$$

$$\frac{\partial}{\partial y} f = x$$

#1b) Using #1a and the chain rule:

$$\frac{\partial}{\partial x} f = ye^{xy}$$

$$\frac{\partial}{\partial y} f = xe^{xy}$$

#1c) We use the product rule for the first one:

$$\frac{\partial}{\partial x} f = \cos x \cos y + x(-\sin x \cos y) = (\cos x - x \sin x) \cos y$$

$$\frac{\partial}{\partial y} f = x \cos x (-\sin y) = -x \cos x \sin y$$

#3a) The product rule and chain rules are used here:

$$\frac{\partial}{\partial x} w = e^{x^2+y^2} + x(2x)e^{x^2+y^2} = (1 + 2x^2)e^{x^2+y^2}$$

$$\frac{\partial}{\partial y} w = x(2y)e^{x^2+y^2} = 2xye^{x^2+y^2}$$

#3d) We have to assume that  $y \neq 0$ . Using  $w = xy^{-1}$ , we use the power rule for the second:

$$\frac{\partial}{\partial x} w = \frac{1}{y}$$

$$\frac{\partial}{\partial y} w = -\frac{x}{y^2}$$

#7a)

$$f_1(x, y) = x \text{ and } f_2(x, y) = y$$

$$\frac{\partial}{\partial x} f_1 = 1$$

$$\frac{\partial}{\partial y} f_1 = 0$$

$$\frac{\partial}{\partial x} f_2 = 0$$

$$\frac{\partial}{\partial y} f_2 = 1$$

$$Df = \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix}$$

#7b)

$$f_1(x, y) = xe^y + \cos y, f_2(x, y) = x, f_3(x, y) = x + e^y$$

$$\frac{\partial}{\partial x} f_1 = e^y \text{ and } \frac{\partial}{\partial y} f_1 = xe^y - \sin y$$

$$\frac{\partial}{\partial x} f_2 = 1 \text{ and } \frac{\partial}{\partial y} f_2 = 0$$

$$\frac{\partial}{\partial x} f_3 = 1 \text{ and } \frac{\partial}{\partial y} f_3 = e^y$$

$$Df = \begin{pmatrix} e^y & xe^y - \sin y \\ 1 & 0 \\ 1 & e^y \end{pmatrix}$$

## Section 2.4

**#3)** This is a line in  $\mathbb{R}^3$  that passes through  $(-1, 2, 0)$  and  $(1, 3, 1)$ . To see this, note that this equation looks a lot like the parametrized line equation that we discussed in **Chapter 1**.

**#8)**

$$\vec{r}(t) = \begin{pmatrix} 4e^t \\ 6(4t^3) \\ -\sin t \end{pmatrix} = \begin{pmatrix} 4e^t \\ 24t^3 \\ -\sin t \end{pmatrix}$$

**#9)**

$$\vec{c}(t) = \begin{pmatrix} e^t \\ -\sin t \end{pmatrix}$$

## Section 2.5

#2a)

$$\frac{\partial}{\partial x}f = 0 \text{ and } \frac{\partial}{\partial y}f = 0$$

Both partials are **continuous**  $\Rightarrow f$  is **differentiable**.

#2e)

$$\frac{\partial}{\partial x}f = ye^{xy} \text{ and } \frac{\partial}{\partial y}f = xe^{xy}$$

Both partials are **continuous**  $\Rightarrow f$  is **differentiable**.

#2g)

$$\frac{\partial}{\partial x}f = 4x^3 \text{ and } \frac{\partial}{\partial y}f = -4y^3$$

Both partials are **continuous**  $\Rightarrow f$  is **differentiable**.

#4) Let's first use the chain rule to figure out what we want to verify. In order to see what we get for  $h_x$ , we'll define a function

$$g(x, y) = \begin{pmatrix} u(x, y) \\ v(x, y) \end{pmatrix}$$

So now

$$h(x, y) = f(u(x, y), v(x, y)) = (f \circ g)(x, y)$$

By the chain rule,

$$\begin{aligned} (h_x \quad h_y) &= \nabla h = \nabla(f \circ g) = \nabla f \bullet Dg = (f_u \quad f_v) \begin{pmatrix} u_x & u_y \\ v_x & v_y \end{pmatrix} \\ &= (f_u u_x + f_v v_x \quad f_u u_y + f_v v_y) \end{aligned}$$

So we are trying to verify  $h_x = f_u u_x + f_v v_x$ .

$$h(x, y) = f(u(x, y), v(x, y)) = \frac{(e^{-x-y})^2 + (e^{xy})^2}{(e^{-x-y})^2 + (e^{xy})^2} = \frac{e^{-2x-2y} + e^{2xy}}{e^{-2x-2y} - e^{2xy}}$$

$$h_x = \frac{(e^{-2x-2y} - e^{2xy}) \frac{\partial}{\partial x}(e^{-2x-2y} + e^{2xy}) - (e^{-2x-2y} + e^{2xy}) \frac{\partial}{\partial x}(e^{-2x-2y} - e^{2xy})}{(e^{-2x-2y} - e^{2xy})^2}$$

$$\begin{aligned}
&= \frac{(e^{-2x-2y} - e^{2xy})(-2e^{-2x-2y} + 2ye^{2xy}) - (e^{-2x-2y} + e^{2xy})(-2e^{-2x-2y} - 2ye^{2xy})}{(e^{-2x-2y} - e^{2xy})^2} \\
&\quad \dots = 4(1-y) \frac{e^{-2x-2y+2xy}}{(e^{-2x-2y} - e^{2xy})^2}
\end{aligned}$$

Remembering the definition of  $u(x, y)$  and  $v(x, y)$ , we can write this as:

$$h_x = 4(1-y) \frac{u^2 v^2}{(u^2 - v^2)^2}$$

Now we will find the RHS (right hand side) of our chain rule identity:

$$\begin{aligned}
f_u &= \frac{(u^2 - v^2) \frac{\partial}{\partial u}(u^2 + v^2) - (u^2 + v^2) \frac{\partial}{\partial u}(u^2 - v^2)}{(u^2 - v^2)^2} \\
&= \frac{(u^2 - v^2)(2u) - (u^2 + v^2)(2u)}{(u^2 - v^2)^2} = -4 \frac{uv^2}{(u^2 - v^2)^2} \\
f_v &= \frac{(u^2 - v^2) \frac{\partial}{\partial v}(u^2 + v^2) - (u^2 + v^2) \frac{\partial}{\partial v}(u^2 - v^2)}{(u^2 - v^2)^2} \\
&= \frac{(u^2 - v^2)(2v) - (u^2 + v^2)(-2v)}{(u^2 - v^2)^2} = 4 \frac{u^2 v}{(u^2 - v^2)^2} \\
u_x &= \frac{\partial}{\partial x} e^{-x-y} = -e^{-x-y} = -u \\
v_x &= \frac{\partial}{\partial x} e^{xy} = ye^{xy} = yv
\end{aligned}$$

So,

$$\begin{aligned}
f_u u_x + f_v v_x &= -4 \frac{uv^2}{(u^2 - v^2)^2} (-u) + 4 \frac{u^2 v}{(u^2 - v^2)^2} (yv) \\
&= 4(1-y) \frac{u^2 v^2}{(u^2 - v^2)^2} = h_x
\end{aligned}$$

□

**#17a)** To get  $G(x, y(x))$  as a composition, we will define  $h : \mathbb{R} \rightarrow \mathbb{R}^2$  as

$$h(x) = \begin{pmatrix} x \\ y(x) \end{pmatrix} \Rightarrow G(x, y(x)) = G \circ h$$

$$(G \circ h)(x) = 0 \Rightarrow \nabla(G \circ h) = \nabla(0) = 0$$

So by the chain rule, we get

$$\begin{aligned} 0 &= \nabla G \bullet Dh(x) = \begin{pmatrix} G_x & G_y \end{pmatrix} \begin{pmatrix} 1 \\ y' \end{pmatrix} \\ &= G_x + G_y y' \Rightarrow y' = -\frac{G_x}{G_y}, G_y \neq 0 \end{aligned}$$

**#17b)** We will use a similar strategy as in #17a, but we now have to make some adjustments.  $G : \mathbb{R}^3 \rightarrow \mathbb{R}^2$  so we will use  $h : \mathbb{R} \rightarrow \mathbb{R}^3$ :

$$G(x, y, z) = \begin{pmatrix} G_1(x, y, z) \\ G_2(x, y, z) \end{pmatrix} \text{ and } h(x) = \begin{pmatrix} x \\ y_1(x) \\ y_2(x) \end{pmatrix}$$

So,

$$0 = G(x, y_1(x), y_2(x)) = (G \circ h)(x) \Rightarrow \nabla(G \circ h) = 0$$

By the chain rule, we get:

$$DG \bullet Dh = \begin{pmatrix} \frac{\partial}{\partial x} G_1 & \frac{\partial}{\partial y} G_1 & \frac{\partial}{\partial z} G_1 \\ \frac{\partial}{\partial x} G_2 & \frac{\partial}{\partial y} G_2 & \frac{\partial}{\partial z} G_2 \end{pmatrix} \begin{pmatrix} 1 \\ y'_1 \\ y'_2 \end{pmatrix} = \begin{pmatrix} \frac{\partial}{\partial x} G_1 + y'_1 \frac{\partial}{\partial y} G_1 + y'_2 \frac{\partial}{\partial z} G_1 \\ \frac{\partial}{\partial x} G_2 + y'_1 \frac{\partial}{\partial y} G_2 + y'_2 \frac{\partial}{\partial z} G_2 \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \end{pmatrix}$$

$$\Rightarrow \begin{pmatrix} y'_1 \frac{\partial}{\partial y} G_1 + y'_2 \frac{\partial}{\partial z} G_1 \\ y'_1 \frac{\partial}{\partial y} G_2 + y'_2 \frac{\partial}{\partial z} G_2 \end{pmatrix} = \begin{pmatrix} -\frac{\partial}{\partial x} G_1 \\ -\frac{\partial}{\partial x} G_2 \end{pmatrix} \Rightarrow \begin{pmatrix} \frac{\partial}{\partial y} G_1 + \frac{\partial}{\partial z} G_1 \\ \frac{\partial}{\partial y} G_2 + \frac{\partial}{\partial z} G_2 \end{pmatrix} \begin{pmatrix} y'_1 \\ y'_2 \end{pmatrix} = \begin{pmatrix} -\frac{\partial}{\partial x} G_1 \\ -\frac{\partial}{\partial x} G_2 \end{pmatrix}$$

Using some linear algebra,

$$\begin{aligned} \begin{pmatrix} y'_1 \\ y'_2 \end{pmatrix} &= \begin{pmatrix} \frac{\partial}{\partial y} G_1 + \frac{\partial}{\partial z} G_1 \\ \frac{\partial}{\partial y} G_2 + \frac{\partial}{\partial z} G_2 \end{pmatrix}^{-1} \begin{pmatrix} -\frac{\partial}{\partial x} G_1 \\ -\frac{\partial}{\partial x} G_2 \end{pmatrix} \\ &= \frac{1}{\frac{\partial}{\partial y} G_1 \frac{\partial}{\partial z} G_2 - \frac{\partial}{\partial z} G_1 \frac{\partial}{\partial y} G_2} \begin{pmatrix} \frac{\partial}{\partial z} G_2 & -\frac{\partial}{\partial y} G_1 \\ -\frac{\partial}{\partial y} G_2 & \frac{\partial}{\partial z} G_1 \end{pmatrix} \begin{pmatrix} -\frac{\partial}{\partial x} G_1 \\ -\frac{\partial}{\partial x} G_2 \end{pmatrix} \end{aligned}$$

Or,

$$y'_1 = \frac{\frac{\partial}{\partial z} G_1 \frac{\partial}{\partial x} G_2 - \frac{\partial}{\partial x} G_1 \frac{\partial}{\partial z} G_2}{\frac{\partial}{\partial y} G_1 \frac{\partial}{\partial z} G_2 - \frac{\partial}{\partial z} G_1 \frac{\partial}{\partial y} G_2}$$

$$y'_2 = \frac{\frac{\partial}{\partial x} G_1 \frac{\partial}{\partial y} G_2 - \frac{\partial}{\partial y} G_1 \frac{\partial}{\partial x} G_2}{\frac{\partial}{\partial y} G_1 \frac{\partial}{\partial z} G_2 - \frac{\partial}{\partial z} G_1 \frac{\partial}{\partial y} G_2}$$

$$\text{for } \frac{\partial}{\partial y} G_1 \frac{\partial}{\partial z} G_2 - \frac{\partial}{\partial z} G_1 \frac{\partial}{\partial y} G_2 \neq 0$$

#17c)

$$y' = -\frac{\frac{\partial}{\partial x}(x^2 + y^3 + e^y)}{\frac{\partial}{\partial y}(x^2 + y^3 + e^y)} = -\frac{2x}{3y^2 + e^y}$$

## Section 2.6

#3b) The directional derivative is

$$\nabla f \bullet \vec{d}$$

where  $\vec{d}$  is a unit vector.

$$\|\vec{d}\| = \sqrt{1^2 + (-1)^2 + 1^2} = \sqrt{3} \neq 1$$

So let

$$\vec{d}_2 = \frac{\vec{d}}{\|\vec{d}\|} = \begin{pmatrix} \frac{1}{\sqrt{3}} \\ -\frac{1}{\sqrt{3}} \\ \frac{1}{\sqrt{3}} \end{pmatrix}$$

$$\nabla f = (e^x \quad z \quad y)$$

$$\nabla f \bullet \vec{d}_2 = (e^x \quad z \quad y) \begin{pmatrix} \frac{1}{\sqrt{3}} \\ -\frac{1}{\sqrt{3}} \\ \frac{1}{\sqrt{3}} \end{pmatrix} = \frac{e^x}{\sqrt{3}} - \frac{z}{\sqrt{3}} + \frac{y}{\sqrt{3}}$$

$$(\nabla f \bullet \vec{d}_2)(1, 1, 1) = \frac{e}{\sqrt{3}} - \frac{1}{\sqrt{3}} + \frac{1}{\sqrt{3}} = \frac{e}{\sqrt{3}}$$

#4b)

$$f(x, y, z) = y^2 - x^2 \Rightarrow \nabla f = (-2x \quad 2y \quad 0)$$

$$\vec{x}_0 = \begin{pmatrix} 1 \\ 2 \\ 8 \end{pmatrix} \Rightarrow \nabla f(\vec{x}_0) = (-2, 4, 0)$$

$$\nabla f(\vec{x}_0) \bullet (\vec{x} - \vec{x}_0) = 0 \Rightarrow -2(x - 1) + 4(y - 2) + 0(z - 8) = 0$$

$$\text{or } -(x - 1) + 2(y - 2) = 0$$

$$\text{or } -x + 2y - 3 = 0$$

#4c)

$$f(x, y, z) = xyz \Rightarrow \nabla f = (yz \quad xz \quad xy)$$

$$\vec{x}_0 = \begin{pmatrix} 1 \\ 1 \\ 1 \end{pmatrix} \Rightarrow \nabla f(\vec{x}_0) = (1, 1, 1)$$

$$\nabla f(\vec{x}_0) \bullet (\vec{x} - \vec{x}_0) = 0 \Rightarrow (x - 1) + (y - 1) + (z - 1) = 0$$

$$\text{or } x + y + z - 3 = 0$$

#19) Let us look at some even function that we know:

$$f(x) = \cos x \Rightarrow \nabla f(0) = f'(0) = -\sin 0 = 0$$

$$f(x) = x^2 \Rightarrow \nabla f(0) = f'(0) = 2(0) = 0$$

Let's try a multivariable example:

$$f(x, y) = \sin x \sin y \Rightarrow \nabla f(\vec{0}) = (\cos 0 \sin 0 + \sin 0 \cos 0) = \vec{0}$$

So our guess would be that  $\nabla f(\vec{0}) = \vec{0}$ .

*This is one of the proofs listed on the website.*