

Math 211

Lecture #19

November 2, 2000

Planar System $\mathbf{x}' = A\mathbf{x}$

Equilibrium points for the system

- The set of equilibrium points equals $\text{null}(A)$.
- If A is nonsingular $\mathbf{0}$ is the only equilibrium point.
- Can we list the types of all possible equilibrium points for planar linear systems?
- The complete list is the second project.
- To do this we look at solution curves in the phase plane.

Planar System $\mathbf{x}' = A\mathbf{x}$

- With distinct real eigenvalues.
- $p(\lambda) = \lambda^2 - T\lambda + D$ with $T^2 - 4D > 0$.

$$\lambda_1 = \frac{T - \sqrt{T^2 - 4D}}{2} < \lambda_2 = \frac{T + \sqrt{T^2 - 4D}}{2}$$

- Eigenvectors \mathbf{v}_1 and \mathbf{v}_2 . General solution

$$\mathbf{x}(t) = C_1 e^{\lambda_1 t} \mathbf{v}_1 + C_2 e^{\lambda_2 t} \mathbf{v}_2$$

Exponential Solutions

$$\mathbf{x}(t) = Ce^{\lambda t} \mathbf{v}$$

- The solution curve is a straight half-line through $C\mathbf{v}$.
- If $\lambda > 0$ the solution starts at $\mathbf{0}$ for $t = -\infty$, and tends to ∞ as $t \rightarrow \infty$. **Unstable solution**
- If $\lambda < 0$ the solution starts at ∞ for $t = -\infty$, and tends to $\mathbf{0}$ as $t \rightarrow \infty$. **Stable solution**
- Sometimes called **half-line** solutions.

Saddle Point

- $\lambda_1 < 0 < \lambda_2$
- General solution $\mathbf{x}(t) = C_1 e^{\lambda_1 t} \mathbf{v}_1 + C_2 e^{\lambda_2 t} \mathbf{v}_2$
- Two stable exponential solutions ($C_2 = 0$) and two unstable exponential solutions ($C_1 = 0$).
- As $t \rightarrow \infty$, $\mathbf{x}(t) \rightarrow \infty$ approaching the half line through $C_2 \mathbf{v}_2$.
- As $t \rightarrow -\infty$, $\mathbf{x}(t) \rightarrow \infty$ approaching the half line through $C_1 \mathbf{v}_1$.

Nodal Sink

- $\lambda_1 < \lambda_2 < 0$
- General solution

$$\mathbf{x}(t) = C_1 e^{\lambda_1 t} \mathbf{v}_1 + C_2 e^{\lambda_2 t} \mathbf{v}_2$$

- Stable exponential solutions.
- All solutions $\rightarrow \mathbf{0}$ as $t \rightarrow \infty$. If $C_2 \neq 0$ tangent to $C_2 \mathbf{v}_2$. All solutions are stable.
- All solutions $\rightarrow \infty$ as $t \rightarrow -\infty$. If $C_1 \neq 0$ parallel to the half line through $C_1 \mathbf{v}_1$.

Nodal Source

- $0 < \lambda_1 < \lambda_2$
- General solution

$$\mathbf{x}(t) = C_1 e^{\lambda_1 t} \mathbf{v}_1 + C_2 e^{\lambda_2 t} \mathbf{v}_2$$

- Exponential solutions are unstable.
- All solutions $\rightarrow \mathbf{0}$ as $t \rightarrow -\infty$. If $C_1 \neq 0$ tangent to $C_1 \mathbf{v}_1$. All solutions are unstable.
- All solutions $\rightarrow \infty$ as $t \rightarrow -\infty$. If $C_2 \neq 0$ parallel to the half line through $C_2 \mathbf{v}_2$.

Planar System $\mathbf{x}' = A\mathbf{x}$

- Complex eigenvalues , $\lambda = \alpha + i\beta$ and $\bar{\lambda} = \alpha - i\beta$. ($T^2 - 4D < 0$)
- Eigenvector $\mathbf{w} = \mathbf{v}_1 + i\mathbf{v}_2$ associated to λ .
- General real solution

$$\begin{aligned}\mathbf{x}(t) = & C_1 e^{\alpha t} [\cos \beta t \cdot \mathbf{v}_1 - \sin \beta t \cdot \mathbf{v}_2] \\ & + C_2 e^{\alpha t} [\sin \beta t \cdot \mathbf{v}_1 + \cos \beta t \cdot \mathbf{v}_2]\end{aligned}$$

Center

- $\alpha = \operatorname{Re}(\lambda) = 0$
- General real solution

$$\begin{aligned}\mathbf{x}(t) = & C_1[\cos \beta t \cdot \mathbf{v}_1 - \sin \beta t \cdot \mathbf{v}_2] \\ & + C_2[\sin \beta t \cdot \mathbf{v}_1 + \cos \beta t \cdot \mathbf{v}_2]\end{aligned}$$

- Every solution is periodic with period $T = 2\pi/\beta$.
- All solution curves are ellipses.

Spiral Sink

- $\alpha = \operatorname{Re}(\lambda) < 0$
- General real solution

$$\begin{aligned}\mathbf{x}(t) = & C_1 e^{\alpha t} [\cos \beta t \cdot \mathbf{v}_1 - \sin \beta t \cdot \mathbf{v}_2] \\ & + C_2 e^{\alpha t} [\sin \beta t \cdot \mathbf{v}_1 + \cos \beta t \cdot \mathbf{v}_2]\end{aligned}$$

- All solutions spiral into $\mathbf{0}$ as $t \rightarrow \infty$.

Spiral Source

- $\alpha = \operatorname{Re}(\lambda) > 0$
- General real solution

$$\begin{aligned}\mathbf{x}(t) = & C_1 e^{\alpha t} [\cos \beta t \cdot \mathbf{v}_1 - \sin \beta t \cdot \mathbf{v}_2] \\ & + C_2 e^{\alpha t} [\sin \beta t \cdot \mathbf{v}_1 + \cos \beta t \cdot \mathbf{v}_2]\end{aligned}$$

- All solutions spiral into $\mathbf{0}$ as $t \rightarrow -\infty$.

Trace-Determinant Plane

$$A = \begin{pmatrix} a_{11} & a_{12} \\ a_{21} & a_{22} \end{pmatrix}; \quad p(\lambda) = \lambda^2 - T\lambda + D$$

- Eigenvalues $\lambda_1, \lambda_2 = \frac{T \pm \sqrt{T^2 - 4D}}{2}$.

$$\begin{aligned} p(\lambda) &= (\lambda - \lambda_1)(\lambda - \lambda_2) \\ &= \lambda^2 - (\lambda_1 + \lambda_2)\lambda + \lambda_1\lambda_2 \end{aligned}$$

- $T = \lambda_1 + \lambda_2$ and $D = \lambda_1\lambda_2$.
- Duality between (λ_1, λ_2) and (T, D) .

Trace-Determinant Plane (cont.)

- $T^2 - 4D > 0 \Rightarrow$ real eigenvalues λ_1 & λ_2
 - ◇ $D = \lambda_1 \lambda_2 < 0 \Rightarrow$ Saddle point.
 - ◇ $D = \lambda_1 \lambda_2 > 0 \Rightarrow$ Eigenvalues have the same sign.
 - ★ $T = \lambda_1 + \lambda_2 > 0$ Nodal source.
 - ★ $T = \lambda_1 + \lambda_2 < 0$ Nodal sink.

Trace-Determinant Plane (cont.)

- $T^2 - 4D < 0 \Rightarrow$ complex eigenvalues

$$\lambda = \alpha + i\beta \quad \text{and} \quad \bar{\lambda} = \alpha - i\beta.$$

- ◇ $T = \lambda + \bar{\lambda} = 2\alpha > 0 \Rightarrow$ Spiral source
- ◇ $T = \lambda + \bar{\lambda} = 2\alpha < 0 \Rightarrow$ Spiral sink
- ◇ $T = \lambda + \bar{\lambda} = 2\alpha = 0 \Rightarrow$ Center

Generic and Nongeneric Equilibrium Points

- Generic types
 - ◇ Saddle, nodal source, nodal sink, spiral source, and spiral sink.
 - ◇ All occupy large open subsets of the trace-determinant plane.
- Nongeneric types
 - ◇ Center and all others. Occupy pieces of the boundaries.

Higher Dimensional Systems

$$\mathbf{x}' = A\mathbf{x}$$

- A is an $n \times n$ real matrix.
- If λ is an eigenvalue and $\mathbf{v} \neq 0$ is an associated eigenvector, then $\mathbf{x}(t) = e^{\lambda t}\mathbf{v}$ is a solution.

Proposition: Suppose that $\lambda_1, \dots, \lambda_k$ are distinct eigenvalues of A , and that $\mathbf{v}_1, \dots, \mathbf{v}_k$ are associated nonzero eigenvectors. Then $\mathbf{v}_1, \dots, \mathbf{v}_k$ are linearly independent.

Theorem: Suppose the $n \times n$ real matrix A has n distinct eigenvalues $\lambda_1, \dots, \lambda_n$, and that $\mathbf{v}_1, \dots, \mathbf{v}_n$ are associated nonzero eigenvectors. Then the exponential solutions $\mathbf{x}_i(t) = e^{\lambda_i t} \mathbf{v}_i$, $1 \leq i \leq n$ form a fundamental system of solutions for the system $\mathbf{x}' = A\mathbf{x}$.

- Example

$$A = \begin{pmatrix} 17 & -30 & -8 \\ 16 & -29 & -8 \\ -12 & 24 & 7 \end{pmatrix}$$